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1. A variable compression piston assembly,
comprising:
a plurality of pistons,
a transition arm coupled to each of the pistons, the
transition arm including a drive member, and
a rotating member coupled to the drive member and
mounted for pivoting movement to slide along an axis of the
drive member, wherein movement of the rotating member
relative to the drive member changes the compression ratio
of the piston assembly.

2. The assembly of claim 1 wherein each of the
pistons comprises a double ended piston.

3. The assembly of claim 2 wherein the transition
arm is coupled to each of the double ended pistons at
approximately a center of each double ended piston.

4. The assembly of claim 1 wherein the plurality
of pistons comprises two pistons and the axis of rotation of
the rotating member and axes of the two pistons lie on a
common plane.

5. The assembly of claim 4 wherein each of the
pistons comprises a double ended piston.

6. The assembly of claim 1 wherein the rotating
member comprises a flywheel.

7. The assembly of claim 1 further comprising a
counterweight mounted to the rotating member.

3 providing a plurality of pistons, a transition arm
4 coupled to each of the pistons, and a rotating member
5 coupled to a drive member of the transition arm and mounted
6 for pivoting movement to slide along an axis of the drive
7 member, and
8 pivoting the rotating member to change the
9 compression ratio of the piston assembly.

1 17. A method of increasing the efficiency of a
2 piston assembly, comprising:
3 providing a plurality of double ended pistons, a
4 transition arm coupled to each of the double ended pistons
5 at approximately a center of each of the double ended
6 pistons, and a rotating member coupled to a drive member of
7 the transition arm and mounted for pivoting movement to
8 slide along an axis of the drive member, and
9 pivoting the rotating member to change the
10 compression ratio of the double ended piston assembly.

1 18. A joint for positioning between first and
2 second elements, the first and second elements being
3 arranged for linear motion along a common axis, comprising:
4 an outer member configured for movement relative to
5 the first and second elements along a first axis
6 perpendicular to the common axis, the outer member defining
7 an opening for receiving a drive arm, and
8 an inner member mounted within the outer member for
9 rotation relative to the outer member about a second axis
10 perpendicular to the first axis and the common axis, the
11 inner member defining an opening for receiving the drive
12 arm.

1 19. The joint of claim 18 wherein the outer member
2 is configured for movement relative to the first and second
3 elements along the second axis.

1 20. The joint of claim 18 wherein the outer member
2 defines first and second parallel flat sides, each flat side
3 defining a plane perpendicular to the common axis.

1 21. The joint of claim 20 further comprising first
2 and second sliding members, the first sliding member for
3 positioning between the first flat side and the first
4 element, the second sliding member for positioning between
5 the second flat side and the second element.

1 22. The joint of claim 20 wherein the first and
2 second flat sides each comprise a polished surface.

1 23. The joint of claim 18 wherein the first and
2 second elements each comprise a piston.

1 24. The joint of claim 18 wherein the first element
2 comprises a piston and the second element comprises a guided
3 rod.

1 25. The joint of claim 18 wherein the drive arm
2 defines a longitudinal axis, the joint further comprising a
3 mount for holding the drive arm axially stationary while
4 permitting the drive arm to rotate about its longitudinal
5 axis.

1 26. The joint of claim 25 wherein the mount
2 comprises a cap screw.

27. The joint of claim 18 wherein the opening in the inner member comprises a channel defining a channel axis perpendicular to the second axis.

1 28. The joint of claim 18 wherein the opening in
2 the outer member comprises a slot for accommodating movement
3 of the drive arm when the inner member rotates relative to
4 outer member.

1 29. The joint of claim 18 further comprising a
2 thrust bearing for receiving an axial load transferred to
3 the drive arm by the first and second elements.

1 30. The joint of claim 18 further comprising a
2 sleeve bearing for receiving a normal load transferred to
3 the drive arm by the first and second elements.

1 31. The joint of claim 18 further comprising a
2 bearing located between the inner and outer members.

1 32. The joint of claim 18 further comprising a
2 connector for mounting of the first and second elements
3 thereto, the connector defining a cavity, the outer member
4 and the inner member being positioned within the cavity.

1 33. A joint for positioning between first and
2 second pistons of a double ended piston, the first and
3 second pistons being arranged for linear motion along an
4 axis of the double ended piston, the joint comprising:
5 an outer member having first and second parallel
6 flat sides, each flat side defining a plane perpendicular to
7 the double ended piston axis, the outer member being
8 configured for movement relative to the first and second

9 pistons along first and second orthogonal axes, the first
10 and second orthogonal axes being perpendicular to the double
11 ended piston axis, the outer member defining an opening for
12 receiving a drive arm, and

13 an inner member mounted within the outer member for
14 rotation relative to the outer member about the first
15 orthogonal axis, the inner member defining an opening for
16 receiving the drive arm.

1 34. The joint of claim 33 wherein the outer member
2 opening comprises a slot and the inner member opening
3 comprises a channel having a channel axis perpendicular to
4 the first orthogonal axis, the joint further comprising a
5 mount for holding the drive arm axially stationary while
6 permitting the drive arm to rotate about its longitudinal
7 axis.

1 35. The joint of claim 33 further comprising a
2 thrust bearing for receiving an axial load transferred to
3 the drive arm by the first and second pistons, and a sleeve
4 bearing for receiving a normal load transferred to the drive
5 arm by the first and second pistons.

1 36. A piston assembly, comprising:

2 first and second elements configured for linear
3 motion along a common axis, at least one of the first and
4 second elements being a piston,

5 a joint positioned between the first and second
6 elements, the joint including
7 an outer member configured for movement
8 relative to the first and second elements along a first axis
9 perpendicular to the common axis, the outer member defining
10 a opening for receiving a drive pin, and

11 an inner member mounted within the outer member
12 for rotation relative to the outer member about a second
13 axis perpendicular to the first axis and the common axis,
14 the inner member defining an opening for receiving the drive
15 arm.

1 37. A method of reducing side load in a double
2 ended member, the double ended member including first and
3 second elements arranged for linear motion along an axis of
4 the double ended member, the method comprising:
5 providing a joint located between the first and
6 second elements, the joint including an outer member
7 configured for movement relative to the first and second
8 elements along a first axis perpendicular to the double
9 ended member axis, and an inner member mounted within the
10 outer member for rotation relative to the outer member about
11 a second axis perpendicular to the first axis and the double
12 ended member axis,
13 transferring load between the first and second
14 elements and a drive arm mounted to the joint through two
15 opposed surfaces of the outer member.

1 38. A method of reducing side load in a double
2 ended piston assembly, the double ended piston assembly
3 including first and second pistons arranged for linear
4 motion along an axis of the double ended piston, the method
5 comprising:
6 providing a joint located between the first and
7 second pistons and configured to move relative to the first
8 and second pistons along first and second orthogonal axes,
9 the first and second orthogonal axes being perpendicular to
10 the double ended piston axis, the joint defining two opposed
11 flat surfaces, and

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